

Automating OBN surveys with MantaRay™ AUV

PXGEO

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SEAPEX Technology Forum



Marine Towed Streamer

Ocean Bottom Node

Lower operational costs and faster turnaround

Limited azimuthal response

Restricted geometries

Limited offsets

Higher 4D noise

High noise environment

Consistent illumination of the water bottom and shallow over-burden

Higher operational costs and timelines

Full Azimuth response

Unconstrained geometries

Ultra long-offsets

Excellent receiver repeatability*

Low noise environment

Inconsistent illumination of the water bottom

The industry has accepted that ROV-deployed ocean bottom node projects deliver the optimum seismic reflection measurements



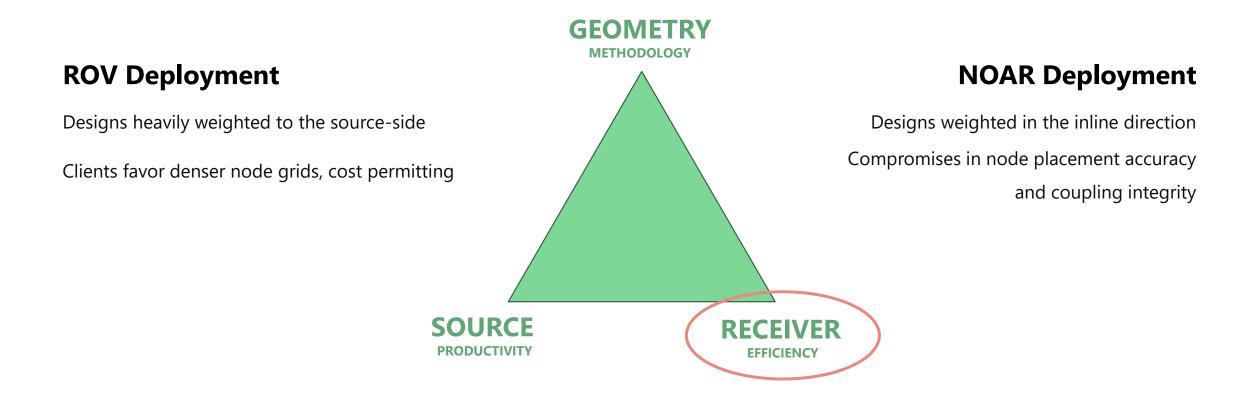
OBN Deployment Technologies

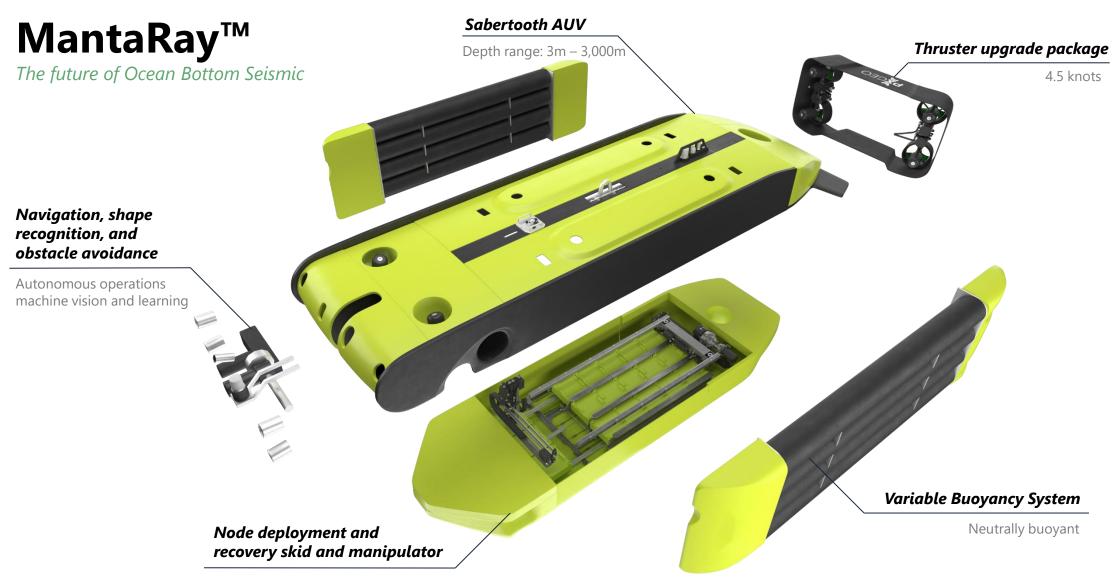
	NoaR	ROV	AUV
Scalable			
Efficient	0		
Water depths	0-xxx	15-3,000 m	3-3,000 m
Coupling	<u> </u>	<u> </u>	0
Repeatability	<u> </u>		
Fold	0		<u> </u>
Design flexibility			
Environment		0	0



Compromises in Current Node Survey Design

Symmetrical sampling is the geophysical ideal



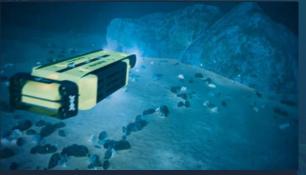


35 x Manta Nodes

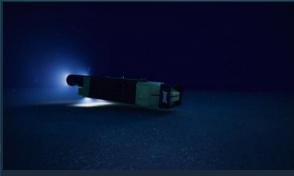
Key elements of MantaRay



Safe Deployment of MantaRay and Garage



Controlled Movement



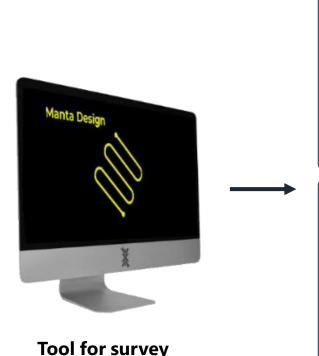
Controlled Node Deployment and Recovery



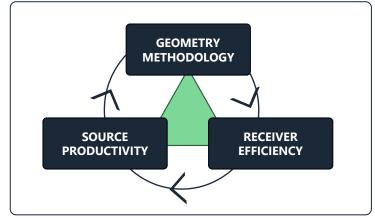
Shape Recognition Camera Technology

Survey Design Flexibility

MantaDesign™

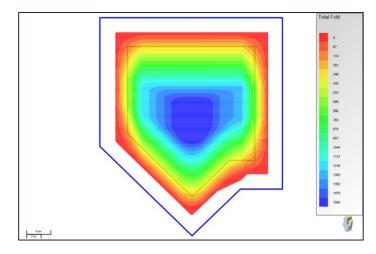


Tool for survey prototyping and time-motion analysis



Time - Motion Studies

Interactive process with client to obtain optimal survey design



Survey design output

What would you do with a faster receiver resource?

Improved sampling and image quality within the same timeframe

Identical sampling within a reduced timeframe

Equivalent sampling within a reduced timeframe



